# Self-similar solutions of the porous medium equation in a half-space with a nonlinear boundary condition: existence and symmetry 

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#### Abstract

We find existence of a nonnegative compactly supported solution of the problem $\Delta u=u^{\alpha}$ in $\mathbb{R}_{+}^{N}$, $\partial u / \partial \nu=u$ on $\partial \mathbb{R}_{+}^{N}$. Moreover, we prove that every nonnegative solution with finite energy is compactly supported and radially symmetric in the tangential variables. © 2004 Elsevier Inc. All rights reserved.

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## 1. Introduction

We study existence of nonnegative solutions of the following problem:

$$
\begin{cases}\Delta u=u^{\alpha} & \text { in } \mathbb{R}_{+}^{N},  \tag{1.1}\\ \frac{\partial u}{\partial \nu}=u & \text { on } \partial \mathbb{R}_{+}^{N},\end{cases}
$$

where $\partial / \partial v$ is the outer unit normal derivative and $0<\alpha<1$.

[^0]This elliptic problem appears naturally when one considers self-similar blowing up solutions of the porous medium equation $(m>1)$

$$
\begin{cases}v_{t}=\Delta v^{m} & \text { in } \mathbb{R}_{+}^{N} \times(0, T)  \tag{1.2}\\ \frac{\partial v^{m}}{\partial v}=v^{m} & \text { on } \partial \mathbb{R}_{+}^{N} \times(0, T)\end{cases}
$$

The blow-up problem for the porous medium equation has deserved a great deal of attention; see, for example, [3,10-12,19].

In the study of blow-up problems, self-similar profiles are used to study the fine asymptotic behavior of a solution of the parabolic equation near its blow-up time; see, for example, $[14,15]$. It often happens that the spatial shape of the solution near blow-up is close to a self-similar profile [5,6,12,15].

In our case, assume that $v(x, t)$ is a solution of (1.2) with blow-up time $T$. Then the rescaled function $z(x, t)=(T-t)^{1 /(m-1)} v(x, t)$ should converge as $t \nearrow T$ to a stationary profile $z(x)$ satisfying

$$
\begin{cases}\Delta z^{m}=\frac{1}{m-1} z & \text { in } \mathbb{R}_{+}^{N}, \\ \frac{\partial z^{m}}{\partial \nu}=z^{m} & \text { on } \partial \mathbb{R}_{+}^{N},\end{cases}
$$

as is often the case when dealing with parabolic problems; see [5-7,10]. Then $u(x)=$ $c z(x)^{m}$ is a solution of (1.1) with $\alpha=1 / m$ for a suitable choice of the constant $c$.

On the other hand, given a nonnegative solution $u(x)$ of $(1.1), z(x)=(u(x) / c)^{1 / m}$ gives rise to a special solution to (1.2) (in self-similar form) blowing up at time $T$, of the form

$$
\begin{equation*}
v(x, t)=(T-t)^{-1 /(m-1)} z(x) \tag{1.3}
\end{equation*}
$$

Remark that in our case the self-similar scaling does not change the spatial variable, and hence the blow-up set of (1.3) is given by the support of $z(x)$.

Therefore there is an interest in studying self-similar profiles, in our case solutions of (1.1).

In order to motivate our study, let us recall what is known for the problem

$$
\begin{equation*}
v_{t}=\Delta v^{m}+v^{m} \quad \text { in } \mathbb{R}^{N} \times(0, T) \tag{1.4}
\end{equation*}
$$

Problem (1.4) admits self-similar solutions of the form (1.3). In this case the profile $z(x)$ is a solution of

$$
\begin{equation*}
0=\Delta z^{m}+z^{m}-\frac{1}{m-1} z \quad \text { in } \mathbb{R}^{N} \tag{1.5}
\end{equation*}
$$

One way to look for solutions of (1.5) is to search for radial ones. The existence of a radial compactly supported nontrivial solution reduces to the study of an ODE and was done in [7,17]. Moreover, a symmetry analysis using moving planes implies that every solution with finite energy has compact support and is composed by a finite number of radial "bumps" located such that their supports do not intersect; see [7,18].

Concerning the existence of solutions of (1.1), let us observe that in one space dimension we are facing an ODE that can be solved explicitly and it turns out that there exists only one compactly supported solution in $\mathbb{R}_{+}$,

$$
\begin{equation*}
u(x)=c_{1}\left(\left(c_{2}-x\right)_{+}\right)^{2 /(1-\alpha)} \tag{1.6}
\end{equation*}
$$

Unfortunately, for $N \geqslant 2$, an easy inspection of problem (1.1) shows that there is no hope to look for radial solutions since they can not verify the boundary condition. Therefore, in the case under study, the elliptic problem remains a PDE that can not be solved by ODE methods.

However, the problem has still some natural symmetry in the tangential variables. In fact, if we call a point $x \in \mathbb{R}_{+}^{N}, x=\left(x^{\prime}, x_{N}\right)\left(x^{\prime} \in \mathbb{R}^{N-1}\right)$, we can search for solutions that are radial in the tangential variables, i.e.,

$$
\begin{equation*}
u(x)=u\left(\left|x^{\prime}\right|, x_{N}\right) \tag{1.7}
\end{equation*}
$$

It has to be noted that this symmetry assumption does not reduce the problem to an ODE.
Our first result reads as follows.

Theorem 1.1. There exists a nontrivial, nonnegative compactly supported solution of (1.1) of the form (1.7).

Next, we use the moving planes device (with a moving plane parallel to the $x_{N}$ direction) to prove the following result.

Theorem 1.2. Let $u \in H^{1}\left(\mathbb{R}_{+}^{N}\right)$ be a nonnegative solution of (1.1) with connected support. Then $u$ is compactly supported and radial in the tangential variables, that is it has the form (1.7).

Remark that this theorem justifies our symmetry assumption in Theorem 1.1.
When this analysis is performed we can obtain some easy corollaries concerning problem (1.2).

Corollary 1.1. Every nonnegative nontrivial solution of (1.2) blows up in finite time.
The proof of this fact follows by contradiction. Assume that $v$ is a global nontrivial solution. As $v$ is a supersolution of the porous medium equation its support expands [20], and eventually covers the support of a self-similar profile $z$. The proof ends just with the use of a comparison argument using a solution of the form (1.3) with $T$ large enough as subsolution.

Corollary 1.2. There exists a solution of (1.2) with a blow-up set composed by an arbitrary number of connected components.

In fact, we may consider a solution of the form (1.3) with a profile $z(x)$ composed by $n$ disjoint copies of the compactly supported solution provided by Theorem 1.1.

Moreover, we conjecture that the self-similar solutions that we have constructed give the asymptotic behavior of any solution of (1.2) as it happens in one space dimension; see [9].

The problem of uniqueness of solutions to (1.1) with compact support remains open. In the case of Eq. (1.5) it is known that solutions with compact support are unique except for translations, see [8], but the argument relies strongly on ODE techniques.

The rest of the paper is organized as follows. In Section 2 we prove our existence result, Theorem 1.1, and in Section 3, we prove our symmetry result, Theorem 1.2.

Throughout the paper, by $C$ we mean a constant that may vary from line to line but remains independent of the relevant quantities.

## 2. Existence of a symmetric solution

In this section we obtain the existence of a nontrivial nonnegative compactly supported solution of (1.1).

The main idea of the proof is to consider the problem in a large half ball $B(0, R)_{+}=$ $\left\{x,|x|<R, x_{N}>0\right\}$ with mixed boundary conditions, namely,

$$
\begin{cases}\Delta u_{R}=\left(u_{R}\right)^{\alpha} & \text { in } B(0, R)_{+},  \tag{2.1}\\ \frac{\partial u_{R}}{\partial v}=u_{R} & \text { on } \partial B(0, R)_{+} \cap\left\{x_{N}=0\right\}, \\ u_{R}=0 & \text { on } \partial B(0, R)_{+} \cap\left\{x_{N}>0\right\} .\end{cases}
$$

And then obtain the desired solution proving that the support of $u_{R}$ verifies

$$
\max _{x \in \operatorname{supp}\left(u_{R}\right)}|x|<R .
$$

Therefore $u_{R}$ is a solution of (1.1).
This approach has already been employed by other authors. For instance, in [4] they prove existence of positive solutions to a nonlinear problem in a half-space by first solving a related problem in a half ball $B_{R}^{+}$and then letting $R \rightarrow \infty$. Our problem is different in that we deal with a non Lipschitz nonlinearity and the solutions we find have compact support.

For $R>0$ let us introduce the notation:

$$
B_{R}^{+}=B(0, R)_{+}, \quad \partial_{1} B_{R}^{+}=\partial B_{R}^{+} \cap\left\{x_{N}=0\right\}, \quad \partial_{2} B_{R}^{+}=\partial B_{R}^{+} \cap\left\{x_{N}>0\right\}
$$

To prove existence of a solution to (2.1) we consider the functional

$$
I_{R}(u)=\frac{\int_{B_{R}^{+}}|\nabla u|^{2}-\int_{\partial_{1} B_{R}^{+}} u^{2}}{\left(\int_{B_{R}^{+}}|u|^{\alpha+1}\right)^{2 /(\alpha+1)}}
$$

on the space

$$
H=\left\{u \in H^{1}\left(B_{R}^{+}\right) \mid \text {such that } u=0 \text { on } \partial_{2} B_{R}^{+}\right\}
$$

equipped with the norm

$$
\|u\|_{H}^{2}=\int_{B_{R}^{+}}|\nabla u|^{2} .
$$

This is indeed a norm on $H$ by Poincare's inequality, which is valid for functions in $H$ since they vanish on a nontrivial part of the boundary of $B_{R}^{+}$.

Lemma 2.1. For every $R$ large enough $I_{R}$ attains a minimum and there is a minimizer $u \geqslant 0, u \not \equiv 0$ which is a solution of (2.1).

Proof. First, let us verify that

$$
\inf _{u \in H, u \neq 0} I_{R}(u)>-\infty
$$

This statement is equivalent to establish the following Sobolev inequality:

$$
\begin{equation*}
\int_{B_{R}^{+}}|\nabla u|^{2}+K\left(\int_{B_{R}^{+}}|u|^{\alpha+1}\right)^{2 /(\alpha+1)} \geqslant \int_{\partial_{1} B_{R}^{+}} u^{2} \quad \forall u \in H \tag{2.2}
\end{equation*}
$$

where $K$ is a constant (it may depend on $R$ ). If (2.2) fails there exists a sequence $u_{n} \in H$ with $\int_{\partial_{1} B_{R}^{+}} u_{n}^{2}=1$ such that

$$
\begin{equation*}
\int_{B_{R}^{+}}\left|\nabla u_{n}\right|^{2}+n\left(\int_{B_{R}^{+}}\left|u_{n}\right|^{\alpha+1}\right)^{2 /(\alpha+1)} \leqslant 1 \quad \forall n \geqslant 1 . \tag{2.3}
\end{equation*}
$$

But then, up to a subsequence, we have $u_{n} \rightharpoonup u$ weakly in $H, u_{n} \rightarrow u$ strongly in $L^{\alpha+1}\left(B_{R}^{+}\right)$and $\left.\left.u_{n}\right|_{\partial_{1} B_{R}^{+}} \rightarrow u\right|_{\partial_{1} B_{R}^{+}}$strongly in $L^{2}\left(\partial_{1} B_{R}^{+}\right)$. Since $\int_{\partial_{1} B_{R}^{+}} u_{n}^{2}=1$ we must have $\int_{\partial_{1} B_{R}^{+}} u^{2}=1$ on one hand, but (2.3) implies that $u=0$, a contradiction.

Let $\lambda_{1}(R)$ denote the first eigenvalue for the problem

$$
\begin{cases}\Delta u=0 & \text { in } B_{R}^{+}  \tag{2.4}\\ \frac{\partial u}{\partial \nu}=\lambda u & \text { on } \partial_{1} B_{R}^{+} \\ u=0 & \text { on } \partial_{2} B_{R}^{+}\end{cases}
$$

and let $\varphi_{1, R}>0$ be the eigenfunction associated to $\lambda_{1}(R)$. Then $\lambda_{1}(R)>0$ and

$$
I_{R}\left(\varphi_{1, R}\right)=\left(\lambda_{1}(R)-1\right) \frac{\int_{\partial_{1} B_{R}^{+}} \varphi_{1, R}^{2}}{\left(\int_{B_{R}^{+}} \varphi_{1, R}^{\alpha+1}\right)^{2 /(\alpha+1)}}
$$

We claim that if $R$ is sufficiently large then the expression above is negative. In fact, observe that $\lambda_{1}(R)$ is given by

$$
\lambda_{1}(R)=\min _{\varphi \in H \backslash\{0\}} \frac{\int_{B_{R}^{+}}|\nabla \varphi|^{2}}{\int_{\partial_{1} B_{R}^{+}} \varphi^{2}}
$$

and a change of variables shows that

$$
\frac{\int_{B_{R}^{+}}|\nabla \varphi|^{2}}{\int_{\partial_{1} B_{R}^{+}} \varphi^{2}}=\frac{1}{R} \frac{\int_{B_{1}^{+}}|\nabla \tilde{\varphi}|^{2}}{\int_{\partial_{1} B_{1}^{+}} \tilde{\varphi}^{2}}
$$

where $\tilde{\varphi}(x)=\varphi(R x)$. Therefore

$$
\begin{equation*}
\lambda_{1}(R)=\frac{\lambda_{1}(1)}{R} \tag{2.5}
\end{equation*}
$$

and this establishes that

$$
\begin{equation*}
\inf I_{R}(u)<0 \tag{2.6}
\end{equation*}
$$

for $R$ sufficiently large.
Let $\left(u_{n}\right)$ be a minimizing sequence for $I_{R}$. We can assume that $\int_{\partial_{1} B_{R}^{+}} u_{n}^{2}=1$. Since $\inf I_{R}<0$ we can also assume that $I_{R}\left(u_{n}\right) \leqslant 0$. Therefore $\int_{B_{R}^{+}}\left|\nabla u_{n}\right|^{2} \leqslant 1$ and hence up to subsequence $u_{n} \rightharpoonup u$ weakly in $H, u_{n} \rightarrow u$ strongly in $L^{\alpha+1}\left(B_{R}^{+}\right)$and $\left.\left.u_{n}\right|_{\partial_{1} B_{R}^{+}} \rightarrow u\right|_{\partial_{1} B_{R}^{+}}$ strongly in $L^{2}\left(\partial_{1} B_{R}^{+}\right)$. Since $\int_{\partial_{1} B_{R}^{+}} u_{n}^{2}=1$ we conclude that $u \not \equiv 0$ and by the lower semicontinuity of $\|\cdot\|_{H}$ under weak convergence in $H$ we see that

$$
\inf I_{R} \leqslant I_{R}(u) \leqslant \liminf _{n \rightarrow \infty} I_{R}\left(u_{n}\right)=\inf I_{R}
$$

Thus $I_{R}$ has minimizer $u \not \equiv 0$ and we can assume that $u \geqslant 0$. There is a Lagrange multiplier $\lambda$ such that

$$
\int_{B_{R}^{+}} \nabla u \nabla \varphi-\int_{\partial_{1} B_{R}^{+}} u \varphi=\lambda \int_{B_{R}^{+}} u^{\alpha} \varphi \quad \forall \varphi \in H .
$$

Using this with $\varphi=u$ we see that $\lambda$ has the same sign as $I_{R}(u)$, and thus $\lambda<0$. Choosing $\theta=(-\lambda)^{\alpha-1}>0$ it is easy to verify that $\theta u$ solves (2.1). Finally note that $\theta u$ is also a minimizer of $I_{R}$.

Remark 2.1. From the previous proof we may observe that $\inf I(u)<0$ if and only if there exists a nontrivial nonnegative solution of (2.1). Moreover this occurs if and only if $\lambda_{1}(R)<1$.

Lemma 2.2. Let $u_{R}$ be a nonnegative minimizer of $I_{R}$. Then for $R$ large enough there exists $C$ independent of $R$ such that $\left\|u_{R}\right\|_{L^{\alpha+1}\left(B_{R}^{+}\right)} \leqslant C,\left\|u_{R}\right\|_{L^{\infty}\left(B_{R}^{+}\right)} \leqslant C$, and $\left\|\nabla u_{R}\right\|_{L^{\infty}\left(B_{R / 2}^{+}\right)} \leqslant C$.

Proof. The first step is to show that

$$
\begin{equation*}
\int_{B_{R}^{+}} u_{R}^{\alpha+1} \leqslant C \tag{2.7}
\end{equation*}
$$

with $C$ independent of $R$.
Indeed, multiplying (2.1) by $u_{R}$ and integrating by parts we obtain

$$
\begin{equation*}
\int_{B_{R}^{+}}\left|\nabla u_{R}\right|^{2}+u_{R}^{\alpha+1}=\int_{\partial_{1} B_{R}^{+}} u_{R}^{2} \tag{2.8}
\end{equation*}
$$

On the other hand we have shown in (2.6) that $I_{R}<0$ for $R$ large enough, but in fact we have more. Indeed fix $R_{0}$ so that $\lambda_{1}\left(R_{0}\right)-1<0$, where $\lambda_{1}\left(R_{0}\right)$ is the first eigenvalue for (2.4). Let $\varphi_{1, R_{0}}$ be the first eigenfunction associated to $\lambda_{1}\left(R_{0}\right)$ and extend it by zero to $B_{R}^{+}$. Then for $R>R_{0}$,

$$
\inf I_{R} \leqslant I_{R}\left(\varphi_{1, R_{0}}\right)=\left(\lambda_{1}\left(R_{0}\right)-1\right) \frac{\int_{\partial_{1} B_{R_{0}}^{+}} \varphi_{1, R_{0}}^{2}}{\left(\int_{B_{R_{0}}^{+}} \varphi_{1, R_{0}}^{\alpha+1}\right)^{2 /(\alpha+1)}}=-C_{0}
$$

Thus

$$
\begin{equation*}
\int_{B_{R}^{+}}\left|\nabla u_{R}\right|^{2}+C_{0}\left(\int_{B_{R}^{+}} u_{R}^{\alpha+1}\right)^{2 /(\alpha+1)} \leqslant \int_{\partial_{1} B_{R}^{+}} u_{R}^{2} \tag{2.9}
\end{equation*}
$$

From (2.8) and (2.9) we see that (2.7) follows.
The proof of the uniform estimates $\left\|u_{R}\right\|_{L^{\infty}\left(B_{R}^{+}\right)} \leqslant C$ and $\left\|\nabla u_{R / 2}\right\|_{L^{\infty}\left(B_{R}^{+}\right)} \leqslant C$ is standard. For simplicity let us assume first that $B_{1}\left(x_{0}\right) \subset B_{R}^{+}$. Since $u_{R}^{\alpha} \in L^{(\alpha+1) / \alpha}\left(B_{1}\left(x_{0}\right)\right)$ by $L^{p}$ regularity theory $u_{R} \in W^{2,(\alpha+1) / \alpha}\left(B_{1 / 2}\left(x_{0}\right)\right)$ and then by the Sobolev embedding $u_{R} \in L^{q}\left(B_{1 / 2}\left(x_{0}\right)\right)$ with $1 / q=\alpha /(\alpha+1)-2 / n$. Repeating this argument a finite number of times we deduce the bound in $L^{\infty}$. The bound for $\nabla u_{R}$ in $L^{\infty}$ is similar, using Schauder estimates. Finally the same proof works if $x_{0} \in \partial \mathbb{R}_{+}^{N} \cap B_{R}$. The only point that deserves an explanation is the $L^{p}$ regularity theory for the Laplace equation with the boundary condition $\partial u / \partial v=u$ on $\partial \mathbb{R}_{+}^{N}$. This is well known, but for completeness we present a short proof in Appendix A.

Remark 2.2. The mountain pass theorem of Ambrosetti and Rabinowitz [2] can also be used to prove the existence of a solution to (2.1). Indeed, the functional

$$
F(u)=\frac{1}{2} \int_{B_{R}^{+}}|\nabla u|^{2}+\frac{1}{1+\alpha} \int_{B_{R}^{+}}|u|^{1+\alpha}-\frac{1}{2} \int_{\partial_{1} B_{R}^{+}} u^{2}
$$

satisfies the hypotheses of the theorem. An estimate similar to (2.2),

$$
\frac{1}{2} \int_{B_{R}^{+}}|\nabla u|^{2}+K\left(\int_{B_{R}^{+}}|u|^{1+\alpha}\right)^{2 /(1+\alpha)} \geqslant \int_{\partial_{1} B_{R}^{+}} u^{2} \quad \forall u \in H
$$

shows that if $r$ is small enough and $\|u\|_{H}=r$ then

$$
F_{R}(u) \geqslant \frac{1}{4} \int_{B_{R}^{+}}|\nabla u|^{2}=\frac{1}{4} r^{2} .
$$

On the other hand $F_{R}\left(u_{1}\right)<r^{2} / 4$ and $\left\|u_{1}\right\|_{H} \geqslant r$, where $u_{1}=t \varphi_{1, R}$ with $\varphi_{1, R}$ the first eigenfunction for (2.4) and $t_{1}$ is large.

Finally, the estimates of Lemma 2.2 can also be obtained for the mountain pass solution $u_{\mathrm{mp}}$. It suffices to verify that the critical value of the mountain pass solution $F\left(u_{\mathrm{mp}}\right)$ is bounded independently of $R$.

Remark 2.3. Let us write $x \in \mathbb{R}^{N}$ as $x=\left(x^{\prime}, x_{N}\right)$ with $x^{\prime} \in \mathbb{R}^{N-1}$ and $x_{N} \in \mathbb{R}$. Minimizing $I_{R}$ in the subspace of $H$ consisting of functions $u$ such that

$$
\begin{equation*}
u\left(x^{\prime}, x_{N}\right)=u\left(\left|x^{\prime}\right|, x_{N}\right) \tag{2.10}
\end{equation*}
$$

that is, functions that are radial with respect to $x^{\prime}$, we can find a solution to (2.1) with this property.

Definition 2.1. From now on we let $u_{R} \geqslant 0$ denote a nontrivial solution of (2.1) that satisfies (2.10), obtained by minimizing $I_{R}$ on the space of functions in $H$ satisfying (2.10).

We need now a result which will be proved in the next section.
Lemma 2.3. Let $u_{R}$ be the solution of Definition 2.1. Then $u\left(\left|x^{\prime}\right|, x_{N}\right)$ is decreasing in $\left|x^{\prime}\right|$ and $x_{N}$.

The next result will establish Theorem 1.1.
Lemma 2.4. Let $u_{R}$ denote the solution of Definition 2.1. Then for $R$ large enough $u_{R}$ has compact support.

Proof. As before we will write $x \in \mathbb{R}_{+}^{N}$ as $x=\left(x^{\prime}, x_{N}\right)$ with $x^{\prime} \in \mathbb{R}^{N-1}$ and $x_{N}>0$. First let us show that $u_{R}$ satisfies

$$
\begin{equation*}
u_{R}\left(x^{\prime}, x_{N}\right) \leqslant \frac{C}{\left|x^{\prime}\right|^{(N-1) /(\alpha+1)}\left|x_{N}\right|^{1 /(\alpha+1)}} . \tag{2.11}
\end{equation*}
$$

In fact, by Lemma 2.3,

$$
u_{R}\left(x^{\prime}, x_{N}\right) \leqslant u_{R}\left(y^{\prime}, y_{N}\right) \quad \forall\left|y^{\prime}\right| \leqslant\left|x^{\prime}\right|, 0<y_{N} \leqslant x_{N}
$$

Raising to the power $\alpha+1$ on both sides, integrating in the region $\left\{\left(y^{\prime}, y_{N}\right):\left|y^{\prime}\right| \leqslant\left|x^{\prime}\right|\right.$, $\left.0<y_{N} \leqslant x_{N}\right\}$ and using the estimate of Lemma 2.2 we deduce (2.11).

Let $L$ denote a constant such that $\left\|\nabla u_{R}\right\|_{L^{\infty}\left(B_{R / 2}^{+}\right)}^{+} \leqslant L$ for all $R$ large. By (2.11) there is $R_{1}$ such that for $R \geqslant R_{1}$,

$$
u_{R}\left(x^{\prime}, x_{N}\right) \leqslant 1 / 2 \quad \forall\left|x^{\prime}\right| \geqslant \frac{1}{2 L}, x_{N} \geqslant R_{1}
$$

This together with the Lipschitz bound implies that

$$
u_{R}\left(x^{\prime}, R_{1}\right) \leqslant 1 \quad \forall x^{\prime} .
$$

Consider

$$
\begin{equation*}
w_{1}=a\left(\left(b-x_{N}\right)^{+}\right)^{2 /(1-\alpha)} \tag{2.12}
\end{equation*}
$$

where $f^{+}$denotes the positive part of $f$, that is $f^{+}=\max (f, 0)$ and $a, b$ are determined by

$$
\begin{equation*}
a^{\alpha-1}=\frac{(1-\alpha)^{2}}{2(1+\alpha)}, \quad a\left(b-R_{1}\right)^{2 /(1-\alpha)}=1 \tag{2.13}
\end{equation*}
$$

Then $\Delta w_{1}=w_{1}^{\alpha}$ and $w_{1}\left(R_{1}\right)=1$. We claim that from the maximum principle it follows that $u_{R} \leqslant w_{1}$ in $\left\{x_{N}>R_{1}\right\} \cap B_{R}^{+}$. In fact first note that $w_{1} \geqslant u$ on $\partial\left(\left\{x_{N}>R_{1}\right\} \cap B_{R}^{+}\right)$. Then observe that

$$
0=-\Delta\left(w_{1}-u\right)+w_{1}^{\alpha}-u^{\alpha}=-\Delta\left(w_{1}-u\right)+c(x)\left(w_{1}-u\right)
$$

where

$$
c= \begin{cases}\frac{w_{1}^{\alpha}-u^{\alpha}}{w_{1}-u} \geqslant 0 & \text { if } w_{1} \neq u \\ 0 & \text { if } w_{1}=u\end{cases}
$$

Thus the maximum principle can be applied and from $u_{R} \leqslant w_{1}$ in $\left\{x_{N}>R_{1}\right\} \cap B_{R}^{+}$we deduce that $u\left(x^{\prime}, x_{N}\right)=0$ if $x_{N} \geqslant R_{2}, R \geqslant R_{2}$.

Finally, to prove that the support of $u_{R}$ is bounded in the direction of $x^{\prime}$ we need to apply the maximum principle in a region which has part of its boundary on $\left\{x_{N}=0\right\}$. For an arbitrary region as before the maximum principle may not hold, because of the boundary condition $\partial u / \partial v=u$ on $\left\{x_{N}=0\right\}$. However if the part of the boundary on $\left\{x_{N}=0\right\}$ is small enough the maximum principle is valid.

Lemma 2.5. Let $U \subset \mathbb{R}_{+}^{N}$ be open, bounded with a Lipschitz boundary. Suppose that $w \in$ $H^{1}(U)$ satisfies

$$
\begin{cases}\Delta w \leqslant a(x) w & \text { in } U  \tag{2.14}\\ w \geqslant 0 & \text { on } \partial U \cap\left\{x_{N}>0\right\} \\ \frac{\partial w}{\partial v} \geqslant w & \text { on } \partial U \cap\left\{x_{N}=0\right\}\end{cases}
$$

where $a(x) \geqslant 0$. Then there exists $\delta$ such that, if the $N-1$ dimensional measure $\mid \partial U \cap$ $\left\{x_{N}=0\right\} \mid<\delta$ then we have $w \geqslant 0$ in $U$.

Proof of Lemma 2.4 continued. Let $x_{0} \in \partial \mathbb{R}_{+}^{N}$. We shall show that if $\left|x_{0}\right|$ and $R$ are large enough then $u_{R}=0$ in a neighborhood of $x_{0}$. We utilize Lemma 2.5 with $U=\left\{x_{N}>0\right\} \cap$ $B\left(x_{0}, r_{0}\right)$, with $0<r_{0}<1$ small enough. We are going to construct a suitable comparison function $w_{2}$ which satisfies the following properties:

$$
\begin{align*}
& \Delta w_{2} \leqslant w_{2}^{\alpha} \quad \text { in } D  \tag{2.15}\\
& \frac{\partial w_{2}}{\partial v} \geqslant w_{2} \quad \text { on } \partial D \cap x_{N}=0,  \tag{2.16}\\
& w_{2} \equiv 0 \text { in a neighborhood of } x_{0}, \tag{2.17}
\end{align*}
$$

and

$$
\begin{equation*}
\inf _{\partial D x_{N}>0} w_{2}>0 . \tag{2.18}
\end{equation*}
$$

Write $x_{0}=\left(x_{0}^{\prime}, 0\right)$ and define the coordinate $r=\left|x^{\prime}-x_{0}^{\prime}\right|$. Set

$$
\begin{equation*}
w_{2}=a\left(\left(r^{2}+\left(x_{N}-d\right)^{2}-b\right)^{+}\right)^{2 /(1-\alpha)}, \tag{2.19}
\end{equation*}
$$

where $a, b, d>0$ are going to be fixed below depending only on $r_{0}, N$ and $\alpha$ ( $w_{2}$ is just a radial function about the point $\left(x_{0}^{\prime}, d\right)$ ).

First we deal with (2.16). On $\partial D \cap\left\{x_{N}=0\right\}$ we have

$$
\frac{\partial w_{2}}{\partial v}=-\frac{\partial w_{2}}{\partial x_{N}}=\frac{4 a d}{1-\alpha}\left(\left(r^{2}+d^{2}-b\right)^{+}\right)^{(1+\alpha) /(1-\alpha)}
$$

so that $\partial w_{2} / \partial v \geqslant w_{2}$ is equivalent to

$$
\begin{equation*}
\frac{4 d}{1-\alpha} \geqslant\left(r^{2}+d^{2}-b\right)^{+} \tag{2.20}
\end{equation*}
$$

We choose $d$ such that

$$
\begin{equation*}
\frac{r_{0}}{2}>d>\frac{r_{0}^{2}}{4} \tag{2.21}
\end{equation*}
$$

and thus

$$
\frac{4 d}{1-\alpha}>r_{0}^{2}
$$

Then pick $b$ so that

$$
\begin{equation*}
d^{2}-b<0 \tag{2.22}
\end{equation*}
$$

Therefore for $0 \leqslant r \leqslant r_{0}$, (2.20) holds. Note that condition (2.22) also implies that $r^{2}+$ $\left(x_{N}-d\right)^{2}-b<0$ in a neighborhood of $r=0$ and $x_{N}=0$, so that (2.17) holds.

To verify (2.18) observe that if $r^{2}+x_{N}^{2}=r_{0}^{2}$ then

$$
r^{2}+\left(x_{N}-d\right)^{2}-b=r_{0}^{2}-2 x_{N} d+d^{2}-b \geqslant r_{0}\left(r_{0}-2 d\right)+d^{2}-b .
$$

Because of $(2.21), r_{0}\left(r_{0}-2 d\right)>0$ so we restrict $b$ to have $r_{0}\left(r_{0}-2 d\right)+d^{2}-b>0$ in addition to (2.22).

To achieve (2.15) let us compute

$$
\begin{aligned}
\Delta w_{2}= & \left(w_{2}\right)_{x_{N} x_{N}}+\left(w_{2}\right)_{r r}+\frac{N-2}{r}\left(w_{2}\right)_{r} \\
= & a\left(\left(r^{2}+\left(x_{N}-d\right)^{2}-b\right)^{+}\right)^{2 \alpha /(1-\alpha)} \\
& \times\left[\frac{4 N}{1-\alpha}\left(r^{2}+\left(x_{N}-d\right)^{2}-b\right)^{+}+\frac{8(1+\alpha)}{(1-\alpha)^{2}}\left(r^{2}+\left(x_{N}-d\right)^{2}\right)\right] \\
= & a^{1-\alpha} w_{2}^{\alpha}\left[\frac{4 N}{1-\alpha}\left(r^{2}+\left(x_{N}-d\right)^{2}-b\right)^{+}+\frac{8(1+\alpha)}{(1-\alpha)^{2}}\left(r^{2}+\left(x_{N}-d\right)^{2}\right)\right] .
\end{aligned}
$$

If we choose $a>0$ small enough then $\Delta w_{2} \leqslant w_{2}^{\alpha}$ in $D$.
Let

$$
\varepsilon:=\inf _{\partial D \cap\left\{x_{N}>0\right\}} w_{2}>0 .
$$

By (2.11) we can find $R_{3}$ such that for all $R>R_{3}$,

$$
u_{R}\left(x^{\prime}, x_{N}\right) \leqslant \varepsilon / 2 \quad \forall\left|x^{\prime}\right| \geqslant R_{3}, x_{N} \geqslant \frac{\varepsilon}{2 L}
$$

where $L$ is a uniform Lipschitz constant for $u_{R}$. As argued before, we deduce that

$$
u_{R}\left(x^{\prime}, x_{N}\right) \leqslant \varepsilon \quad \forall\left|x^{\prime}\right|>R_{3}, x_{N}>0 .
$$

Now let $x_{0} \in \partial \mathbb{R}_{+}^{N}$ be such that $\left|x_{0}\right|=R_{3}+r_{0}$ and let $R \geqslant R_{3}+2 r_{0}$. Then we have the hypotheses of Lemma 2.5 and since $-\Delta\left(w_{2}-u_{R}\right)=c(x)\left(w_{2}-u_{R}\right)$ with $c(x) \geqslant 0$, we conclude that $u_{R} \leqslant w_{2}$ in $U=B\left(x_{0}, r_{0}\right) \cap \mathbb{R}_{+}^{N}$. Since $w_{2}$ vanishes in a neighborhood of $x_{0}$ and $x_{0}$ was chosen arbitrarily in $\partial B_{R_{3}+r_{0}} \cap \partial \mathbb{R}_{+}^{N}$, we conclude that $u_{R}$ vanishes in a neighborhood of that set. By monotonicity of $u_{R}$ with respect to $\left|x^{\prime}\right|$ and $x_{N}$ we reach the desired conclusion.

Finally we provide a short argument for Lemma 2.5.
Proof of Lemma 2.5. Let us multiply (2.14) by $w^{-}=-\min (w, 0)$ and integrate in $U$,

$$
\int_{U}\left|\nabla w^{-}\right|^{2}+a(x)\left(w^{-}\right)^{2}-\int_{\partial U \cap\left\{x_{N}=0\right\}}\left(w^{-}\right)^{2} \leqslant 0 .
$$

Then

$$
\begin{aligned}
& \int_{U}\left|\nabla w^{-}\right|^{2}+a(x)\left(w^{-}\right)^{2} \leqslant \int_{\partial U \cap\left\{x_{N}=0\right\}}\left(w^{-}\right)^{2} \\
& \quad \leqslant\left(\int_{\partial U \cap\left\{x_{N}=0\right\}}\left(w^{-}\right)^{\tilde{2}}\right)^{2 / 2}\left|\partial U \cap\left\{x_{N}=0\right\}\right|^{1 /(N-1)},
\end{aligned}
$$

where $\tilde{2}=2(N-1) /(N-2)$ is the critical exponent for the Sobolev trace embedding. Using the Sobolev trace embedding we can bound

$$
\left(\int_{\partial U \cap\left\{x_{N}=0\right\}}\left(w^{-}\right)^{\tilde{2}}\right)^{2 / \tilde{2}} \leqslant C \int_{U}\left|\nabla w^{-}\right|^{2},
$$

where the constant $C$ can be chosen independent of $U$. Hence

$$
\int_{U}\left|\nabla w^{-}\right|^{2}+a(x)\left(w^{-}\right)^{2} \leqslant C\left|\partial U \cap\left\{x_{N}=0\right\}\right|^{1 /(N-1)} \int_{U}\left|\nabla w^{-}\right|^{2}
$$

and if $C\left|\partial U \cap\left\{x_{N}=0\right\}\right|^{1 /(N-1)}<1$ then $w^{-} \equiv 0$ in $U$.

## 3. Symmetry properties

In this section we study symmetry properties of solutions of (1.1). In particular we will show that every solution with finite energy is compactly supported and radial in the tangential variables.

Lemma 3.1. Let $u \in H^{1}\left(\mathbb{R}_{+}^{N}\right)$ be a solution of (1.1). Then the following norms are finite: $\|u\|_{L^{\alpha+1}\left(\mathbb{R}_{+}^{N}\right)},\|u\|_{L^{\infty}\left(\mathbb{R}_{+}^{N}\right)}$, and $\|\nabla u\|_{L^{\infty}\left(\mathbb{R}_{+}^{N}\right)}$.

Proof. By the equation

$$
\int_{\mathbb{R}_{+}^{n}}|\nabla u|^{2}+u^{\alpha+1}=\int_{\partial \mathbb{R}_{+}^{N}} u^{2},
$$

and since $u \in H^{1}\left(\mathbb{R}_{+}^{N}\right)$, we deduce that $\int_{\mathbb{R}_{+}^{n}} u^{\alpha+1}<\infty$. From here the estimates for $u$ and $\nabla u$ in $L^{\infty}$ are obtained as in Lemma 2.2.

Lemma 3.2. Let $u \in H^{1}\left(\mathbb{R}_{+}^{N}\right)$ be a solution of (1.1). Then $u$ is compactly supported.
Proof. First we remark that

$$
\begin{equation*}
\lim _{R \rightarrow \infty_{\mathbb{R}_{+}^{N} \backslash B_{R}}} \sup u=0 . \tag{3.1}
\end{equation*}
$$

We prove this by contradiction, that is we suppose that (3.1) fails. Then there exists $\varepsilon>0$ and a sequence of points $x_{n} \in \overline{\mathbb{R}_{+}^{N}}$ such that $\left|x_{n}\right| \rightarrow \infty$ and $u\left(x_{n}\right) \geqslant \varepsilon$ for all $n$. But, by Lemma 3.1, $\sup _{\mathbb{R}_{+}^{N}}|\nabla u|<\infty$ and therefore there exists $r>0$ independent of $n$ such that $u \geqslant \varepsilon / 2$ on $B_{r}\left(x_{n}\right) \cap \mathbb{R}_{+}^{N}$ for all $n$. By taking a subsequence we can assume that the balls $B_{r}\left(x_{n}\right)$ are disjoint. But this implies that $\int_{\mathbb{R}_{+}^{N}} u^{\alpha+1} \geqslant \sum_{n} \int_{B_{r}\left(x_{n}\right) \cap \mathbb{R}_{+}^{N}} u^{\alpha+1}=\infty$, contradicting Lemma 3.1.

We proceed now with an argument similar to the one of Lemma 2.4. First, by (3.1) we can find $R_{1}>0$ such that

$$
u\left(x^{\prime}, R_{1}\right) \leqslant 1 \quad \text { for all } x^{\prime} \in \mathbb{R}^{N-1} .
$$

Consider now the function $w_{1}$ defined in (2.12). Since $w_{1} \geqslant u$ in $\left\{x_{N}=R_{1}\right\}$ and $\liminf _{|x| \rightarrow \infty} w_{1}-u \geqslant 0$, by the maximum principle we deduce that $u \leqslant w_{1}$ in $\left\{x_{N}>R_{1}\right\}$ and thus there exists $R_{2}>0$ such that $u\left(x^{\prime}, x_{N}\right)=0$ for all $x^{\prime}$ and $x_{N}>R_{2}$. (A direct way of verifying that the maximum principle holds in this situation is as follows: suppose that $\sup _{\left\{x_{N}>R_{1}\right\}} u-w_{1}>0$. Then this supremum is attained at a point $x_{0}=\left(x_{0}^{\prime}, x_{0 N}\right)$ with $x_{0 N}>R_{1}$. Hence $\Delta\left(u-w_{1}\right)\left(x_{0}\right) \leqslant 0$ but on the other hand $\Delta\left(u-w_{1}\right)\left(x_{0}\right)=$ $u\left(x_{0}\right)^{\alpha}-w_{1}\left(x_{0}\right)^{\alpha}>0$, a contradiction.)

Let us show now that if $x^{\prime} \in \mathbb{R}^{N-1}$ with $\left|x^{\prime}\right|$ large enough then $u\left(x^{\prime}, 0\right)=0$. Indeed, first choose $r_{0}>0$ small so that the comparison principle of Lemma 2.5 holds in $B_{r_{0}}(x) \cap \mathbb{R}_{+}^{N}$ for all balls $B_{r_{0}}(x)$ with $x \in \overline{\mathbb{R}_{+}^{N}}$. Given $x_{0} \in \partial \mathbb{R}_{+}^{N}$ we constructed a function $w_{2}$ in (2.19). It satisfies $\inf _{\partial D \cap\left\{x_{N}>0\right\}} w_{2}=\varepsilon>0$ (see (2.18)). Using (3.1) we can find $R_{3}>0$ large so that if $x_{0} \in \partial \mathbb{R}_{+}^{N}$ and $\left|x_{0}\right|>R_{3}$ then $u \leqslant \varepsilon$ on $B_{r_{0}}\left(x_{0}\right) \cap \mathbb{R}_{+}^{N}$. Using the comparison principle Lemma 2.5 in $B_{r_{0}}\left(x_{0}\right) \cap \mathbb{R}_{+}^{N}$ we conclude that $u \leqslant w_{2}$ in this domain and hence $u=0$ in a neighborhood of $x_{0}$.

Finally, to see that $u$ has compact support we take the same expression of (2.12) but we consider it as a function of $x_{k}$ for a direction $k=1, \ldots, N-1$,

$$
w_{3}=a\left(\left(b-x_{k}\right)^{+}\right)^{2 /(1-\alpha)},
$$

where the constants $a, b$ are as in (2.13) and $R_{1}$ is large enough so that $u(x) \leqslant 1$ if $x_{k} \geqslant R_{1}$, $x_{N}>0$. We argue as before, using the maximum principle in the region $\left\{x_{k}>R_{1}\right\} \cap \mathbb{R}_{+}^{N}$ and conclude that $u \leqslant w_{3}$ in $\left\{x_{k}>R_{1}\right\} \cap \mathbb{R}_{+}^{N}$. Therefore $u(x)=0$ for $x_{k}$ large and $x_{N}>0$. Applying the same procedure in the other directions we reach the conclusion of the lemma.

To prove radial symmetry in the tangential variables, we will use the moving planes technique introduced in [13]; see also [7]. To this end first we need to introduce some notation. We will call $\Sigma_{\lambda}=\left\{x \in \mathbb{R} \mid x_{1}>\lambda\right\}, T_{\lambda}$ is the hyperplane $\partial \Sigma_{\lambda}, x^{\lambda}$ is the reflection of $x$ across the plane $T_{\lambda}$, that is $x^{\lambda}=2\left(\lambda-x_{1}\right) e_{1}+x, u_{\lambda}(x)=u\left(x^{\lambda}\right)$ and finally $w_{\lambda}=$ $u_{\lambda}-u$. Also we assume that $D=\operatorname{supp}(u)$ is connected.

Lemma 3.3. If there exists a point $x_{0} \in \Sigma_{\lambda} \cap D$ such that $w_{\lambda}\left(x_{0}\right)=0$, then $w_{\lambda}(x)=0$ for all $x \in \Sigma_{\lambda} \cap D$.

Proof. The proof is almost identical to the one of Lemma 2.1 in [7], with the only remark that if $x_{0} \in \partial \mathbb{R}_{+}^{N}$ is such that $w_{\lambda}\left(x_{0}\right)=0$, then we can use Hopf boundary lemma to deduce that $w_{\lambda} \equiv 0$.

Proof of Theorem 1.2. Let us define $\lambda_{0}$ as follows:

$$
\lambda_{0}=\inf \left\{\lambda \mid w_{\lambda}(x) \geqslant 0 \text { for all } x \in \Sigma_{\lambda}\right\} .
$$

This value $\lambda_{0}$ is well defined and finite due to the compactness of the support of $u$ (Lemma 3.2).

Step 1. First, we observe that $-\infty<\lambda_{0}<\infty$ and $\Sigma_{\lambda_{0}} \cap D \neq \emptyset$.
The first assertion follows from the fact that $u$ is compactly supported. The second one is a direct consequence of the maximum principle in small domains, Lemma 2.5. In fact for $\lambda$ large we have that $\Sigma_{\lambda} \cap D=\emptyset$ therefore $w_{\lambda} \geqslant 0$. While for $-\lambda$ large $\left(\mathbb{R}_{+}^{N} \backslash \Sigma_{\lambda}\right) \cap D=\emptyset$ therefore $w_{\lambda} \nsupseteq 0$. Moreover, there exists $\tilde{\lambda}$ such that $\Sigma_{\tilde{\lambda}} \cap D \cap \partial \mathbb{R}_{+}^{N}$ has small measure, therefore we can apply Lemma 2.5 in $\Sigma_{\tilde{\lambda}} \cap D \cap \mathbb{R}_{+}^{N}$ getting $w_{\tilde{\lambda}} \geqslant 0$.

Step 2. $w_{\lambda_{0}} \equiv 0$ in $\Sigma_{\lambda_{0}} \cap \mathbb{R}_{+}^{N}$.
We prove this by contradiction. If $w_{\lambda_{0}} \not \equiv 0$ then, by Lemma 3.3, $w_{\lambda_{0}}>0$ in $\Sigma_{\lambda_{0}} \cap D$. The objective is to show that if $\lambda<\lambda_{0}$ but very close, then $w_{\lambda} \geqslant 0$ in $\Sigma_{\lambda} \cap D$, which is a contradiction with the definition of $\lambda_{0}$. If $\Sigma_{\lambda} \cap D \cap \partial \mathbb{R}_{+}^{N} \neq \emptyset$ let us fix a compact set $K \subset \Sigma_{\lambda} \cap D \cap \partial \mathbb{R}_{+}^{N}$ such that $\Sigma_{\lambda} \cap D \cap \partial \mathbb{R}_{+}^{N} \backslash K$ has measure less than $\delta / 2$. Since $w_{\lambda_{0}}>0$ in $K$ then $w_{\lambda}>0$ in $K$ for $\lambda$ sufficiently close to $\lambda_{0}$. By the definition of $\lambda_{0}$ for $\lambda<\lambda_{0}$,

$$
D^{-}=\left\{x \in \Sigma_{\lambda}, w_{\lambda}(x)<0\right\} \neq \emptyset
$$

and, by our previous considerations, we have that the measure of $D^{-} \cap \partial \mathbb{R}_{+}^{N}$ is small. Therefore we may apply Lemma 2.5 in $D^{-}$, obtaining that $w_{\lambda} \geqslant 0$ in $D^{-}$, a contradiction.

Step 3. To end the proof of the theorem we just observe that, by Step 2, for any given direction perpendicular to $\partial \mathbb{R}_{+}^{N}$ there exists a plane $T_{\lambda_{0}}$ such that $u$ is symmetric with respect to $T_{\lambda_{0}}$. Since this holds for any direction perpendicular to $\partial \mathbb{R}_{+}^{N}$ we conclude that $u$ must be radial in the tangential variables, $u=u\left(\left|x^{\prime}\right|, x_{N}\right)$.

Proof of Lemma 2.3. The same argument as in the proof of Theorem 1.2, using the moving plane method with planes parallel to the $x_{N}$ direction, shows that if $u_{R} \in H^{1}\left(B_{R}^{+}\right)$is a solution to (2.1) then $u_{R}$ is symmetric with respect to the tangential variables $x^{\prime}$ and that it is decreasing with respect to $\left|x^{\prime}\right|$.

Next we prove that $u_{R}$ is decreasing with respect to $x_{N}$. For this we consider the half space $\Sigma_{\lambda}=\left\{x \in \mathbb{R} \mid x_{N}>\lambda\right\}$ and the hyperplane $T_{\lambda}=\partial \Sigma_{\lambda}$. The reflection across $T_{\lambda}$ is given by $x \mapsto x^{\lambda}=2\left(\lambda-x_{N}\right) e_{N}+x$ and we define $u_{\lambda}(x)=u\left(x^{\lambda}\right)$ and $w_{\lambda}=u_{\lambda}-u$.

For $\lambda \in(R / 2, R) w_{\lambda}$ satisfies $\Delta w_{\lambda}=c(x) w_{\lambda}$ with $c(x) \geqslant 0$ in the region $\Sigma_{\lambda} \cap B_{R}$, and $w_{\lambda}=0$ on $T_{\lambda} \cap B_{R}, w_{\lambda} \geqslant 0$ on $\Sigma_{\lambda} \cap \partial B_{R}$. Hence $w_{\lambda} \geqslant 0$ in $\Sigma_{\lambda} \cap B_{R}$ and we deduce that $u_{R}$ is decreasing with respect to $x_{N}$ in the region $\left\{x_{N}>R / 2\right\} \cap B_{R}$.

If $\lambda \in(0, R / 2) w_{\lambda}$ is defined in $\left\{\lambda<x_{N}<2 \lambda\right\} \cap B_{R}$ and satisfies $w_{\lambda} \geqslant 0$ on $\{\lambda<$ $\left.x_{N}<2 \lambda\right\} \cap \partial B_{R}, w_{\lambda}=0$ on $\left\{x_{N}=\lambda\right\} \cap B_{R}$. Suppose now that $\lambda \in(R / 4, R / 2)$. Then
using that $u_{R}$ is decreasing with respect to $x_{N}$ for $x_{N}>R / 2$ we see that $\partial w_{\lambda} / \partial \nu \geqslant 0$ on $\left\{x_{N}=2 \lambda\right\} \cap B_{R}$. By the maximum principle we deduce that $w_{\lambda} \geqslant 0$ in $\left\{\lambda<x_{N}<\right.$ $2 \lambda\} \cap B_{R}$ and therefore $u_{R}$ is decreasing in this region. Repeating this process we obtain the conclusion.

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## Appendix A. An $L^{p}$ estimate

Let $B_{1}:=B_{1}\left(x_{0}\right)$ be a ball with $x_{0} \in \partial \mathbb{R}_{+}^{N}$ and consider the linear elliptic equation

$$
\begin{cases}\Delta u=f & \text { in } B_{1} \cap \mathbb{R}_{+}^{N},  \tag{A.1}\\ \frac{\partial u}{\partial \nu}=u & \text { on } B_{1} \cap \partial \mathbb{R}_{+}^{N}\end{cases}
$$

What is needed in the proof of Lemma 2.2 is the following result from $L^{p}$ regularity theory.

Lemma A.1. Let $1<p<\infty$ and assume that $f \in L^{p}\left(B_{1} \cap \mathbb{R}_{+}^{N}\right)$ and $u \in W^{2, p}\left(B_{1} \cap \mathbb{R}_{+}^{N}\right)$ satisfies (A.1). Then

$$
\begin{equation*}
\|u\|_{W^{2, p}\left(B_{1 / 2} \cap \mathbb{R}_{+}^{N}\right)} \leqslant C(n, p)\left(\|f\|_{L^{p}\left(B_{1} \cap \mathbb{R}_{+}^{N}\right)}+\|u\|_{L^{p}\left(B_{1} \cap \mathbb{R}_{+}^{N}\right)}\right) \tag{A.2}
\end{equation*}
$$

We present a proof using the following $L^{p}$ estimate which can be found in [1, Theorem 14.1, p. 701].

Theorem A.1. Let $1<p<\infty$, suppose that $g \in W^{1-1 / p, p}\left(\partial \mathbb{R}_{+}^{N}\right)$ and let $v \in W^{2, p}\left(\mathbb{R}_{+}^{N}\right)$ with support in $B_{1}$ satisfy

$$
\begin{cases}\Delta v=f & \text { in } \mathbb{R}_{+}^{N} \\ \frac{\partial v}{\partial v}=g & \text { on } \partial \mathbb{R}_{+}^{N}\end{cases}
$$

Then

$$
\begin{equation*}
\|v\|_{W^{2, p}\left(\mathbb{R}_{+}^{N}\right)} \leqslant C(n, p)\left(\|f\|_{L^{p}\left(\mathbb{R}_{+}^{N}\right)}+\|g\|_{W^{1-1 / p, p}\left(\partial \mathbb{R}_{+}^{N}\right)}+\|v\|_{L^{p}\left(\mathbb{R}_{+}^{N}\right)}\right) . \tag{A.3}
\end{equation*}
$$

Proof of (A.2). (This is an argument adapted from [16, Theorem 9.11].) Let $1 / 2<\rho<1$ and $\eta \in C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$ be such that $0 \leqslant \eta \leqslant 1, \eta \equiv 1$ in $B_{\rho}, \eta \equiv 0$ on $\mathbb{R}^{N} \backslash B_{(1+\rho) / 2},|\nabla \eta| \leqslant$ $C /(1-\rho)$ and $\left|D^{2} \eta\right| \leqslant C /(1-\rho)^{2}$ with $C$ independent of $\rho$. Let $v=\eta u$. Then

$$
\Delta v=f \eta+2 \nabla u \nabla \eta+u \Delta \eta
$$

and

$$
\frac{\partial v}{\partial v}=\left(\frac{\partial \eta}{\partial v}+\eta\right) u
$$

Applying (A.3)

$$
\begin{aligned}
\|u\|_{W^{2, p}\left(B_{\rho}^{+}\right)} & \leqslant C\left(\|f\|_{L^{p}\left(B_{1}^{+}\right)}+\frac{1}{1-\rho}\|u\|_{W^{1, p}\left(B_{(1+\rho) / 2}^{+}\right)}+\frac{1}{(1-\rho)^{2}}\|u\|_{L^{p}\left(B_{(1+\rho) / 2}^{+}\right)}\right. \\
& \left.+\|(\partial \eta / \partial v+\eta) u\|_{W^{1-1 / p, p}\left(\partial \mathbb{R}_{+}^{N}\right)}+\|u\|_{L^{p}\left(B_{(1+\rho) / 2}\right.}^{+}\right)
\end{aligned}
$$

and by the trace inequality

$$
\begin{equation*}
\|u\|_{W^{2, p}\left(B_{\rho}^{+}\right)} \leqslant C\left(\|f\|_{L^{p}\left(B_{1}^{+}\right)}+\frac{1}{1-\rho}\|u\|_{W^{1, p}\left(B_{(1+\rho) / 2}^{+}\right)}+\frac{1}{(1-\rho)^{2}}\|u\|_{L^{p}\left(B_{(1+\rho) / 2}^{+}\right)}\right) \tag{A.4}
\end{equation*}
$$

Define the weighted norm

$$
|[u]|_{k, p}=\sup _{1 / 2<\rho<1}(1-\rho)^{k}\|u\|_{W^{k, p}\left(B_{\rho}^{+}\right)} .
$$

Then from (A.4) we get

$$
|[u]|_{2, p} \leqslant C\left(\|f\|_{L^{p}\left(B_{1}^{+}\right)}+|[u]|_{1, p}+|[u]|_{0, p}\right) .
$$

Using the following interpolation inequality (see [16]):

$$
|[u]|_{1, p} \leqslant \varepsilon|[u]|_{2, p}+\frac{C}{\varepsilon}|[u]|_{0, p},
$$

we get (A.2).

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